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Appl. No. 10/520,318  
Amdt dated March 22, 2007Reply to Office Action of December 29, 2006  
Attorney Docket 17932AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

1-9. (Cancelled)

10. (Currently Amended) A method of operating a harvesting machine comprising the steps of:

substantially continuously optimizing a stochastic parameter that characterizes the substantially continuously prevailing readiness with which the harvesting machine processes crop; and substantially continuously adjusting a performance variable of the harvesting machine in dependence on the instantaneous, optimized value of said parameter, in order to optimize the u load of the harvesting machine so as to keep a value  $y(t)$  indicative of the effectiveness of said harvesting machine below a predetermined value, wherein the step of adjusting a performance variable of the harvesting machine occurs in dependence on the output of an inverted form of a yield loss estimation function:

$$\hat{y}(t, \theta) = \exp(\theta u(t)) - 1 \quad (B)$$

11. (Original) A method according to Claim 10, wherein:

processing the crop comprises separating useable crop parts from other plant matter;  
optimizing the load of the harvesting machine comprises optimizing the feedrate  $u(t)$  of crop into the harvesting machine; and  
the effectiveness value comprises losses  $y(t)$  of useable crop parts.

12. (Currently Amended) A method according to Claim 10, wherein the step of continuously optimizing a stochastic parameter includes the step of recursively calculating

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the optimized parameter value in accordance with the following algorithm:

$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \epsilon(t, \hat{\theta}(t-1))) \quad - (A)$$

wherein:

$\hat{\theta}(t)$  is the optimized stochastic parameter value at time  $t$ ; and

$\epsilon(t, \hat{\theta}(t))$  is an error prediction function

~~carrying out the method steps of Claim 1.~~

13. (Cancelled)

14. (Currently Amended) A method according to Claim 10, wherein adjusting a performance variable comprises adjusting ~~the~~a travel speed of said harvesting machine or the ~~an~~ actual cutting width of a header of said harvesting machine.

15. (Currently Amended) A method of mapping one or more field lots for variations in a stochastic parameter that characterizes the instantaneously prevailing readiness with which crop is processed in a harvesting machine, the method comprising the steps of:

operating a harvesting machine to harvest crop in a field lot;

simultaneously measuring ~~the~~a machine load and the machine effectiveness and determining the position of the machine in the field lot;

storing data indicative of the position of the harvesting machine at time  $t$ ;

using the measured machine load data  $u(t)$ , and machine effectiveness data  $y(t)$  in an optimization of said parameter; and

mapping the optimized parameter values obtained from the step of using the measured machine load data  $u(t)$  and machine effectiveness data  $y(t)$  in an optimization of said parameter; so as to produce a parameter map of the field lot.

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16. (Currently Amended) A method according to Claim 15, wherein the step of using the measured machine load data  $u(t)$ , and machine effectiveness data  $y(t)$  in an optimization of said parameter includes the step of recursively calculating the optimized parameter value in accordance with the following algorithm:

$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \varepsilon(t, \hat{\theta}(t-1))) \quad - (A)$$

wherein:

$\hat{\theta}(t)$  is the optimized stochastic parameter value at time  $t$ ; and

$\varepsilon(t, \hat{\theta}(t))$  is an error prediction function carrying out an optimization according to

Claim 1.

17-21. (Cancelled)